

# **PySDM: Pythonic particle-based cloud microphysics package**

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Jagiellonian University in Kraków

# Introduction

# PySDM



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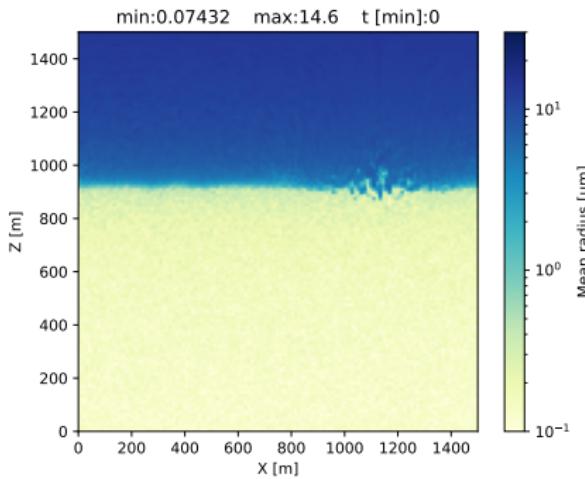
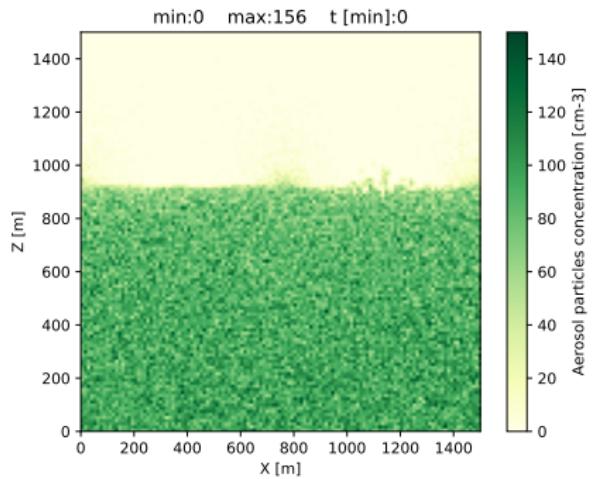
ACSG: Sylwester Arabas, Piotr Bartman, Michael Olesik

# Aerosol-cloud-precipitation interactions



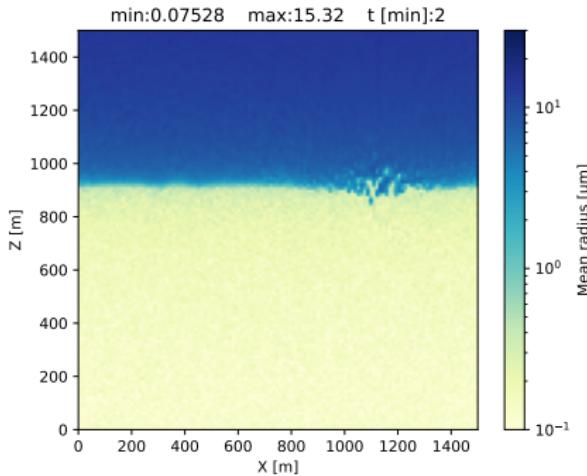
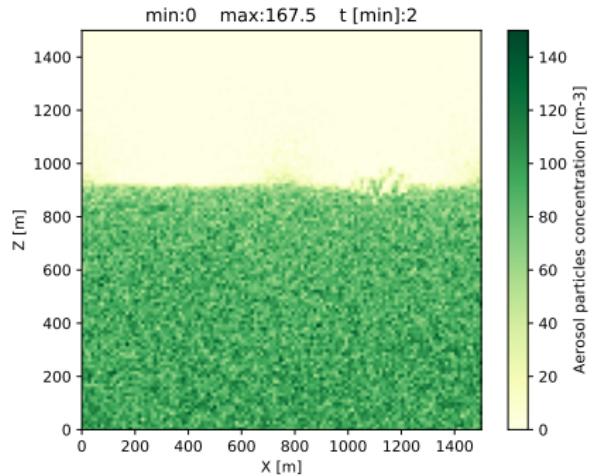
"Cloud and ship. Ukraine, Crimea, Black sea, view from Ai-Petri mountain"  
(photo: Yevgen Timashov / National Geographic)

# Simulation of stratocumulus and virga phenomenon



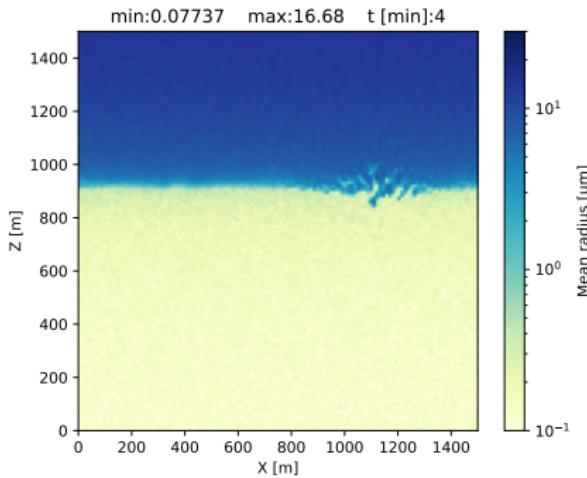
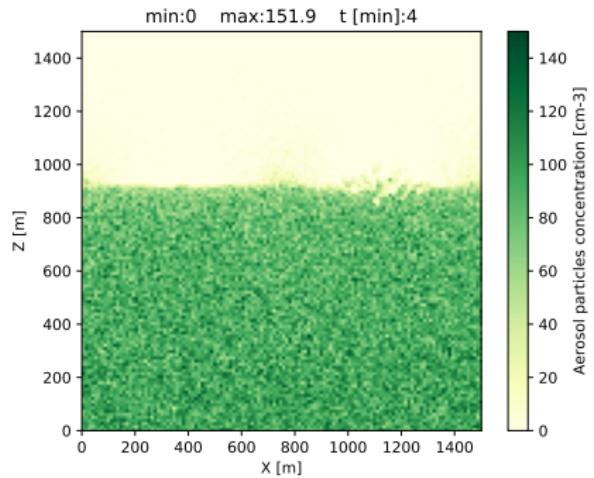
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Computational particles:  $2^{21}$

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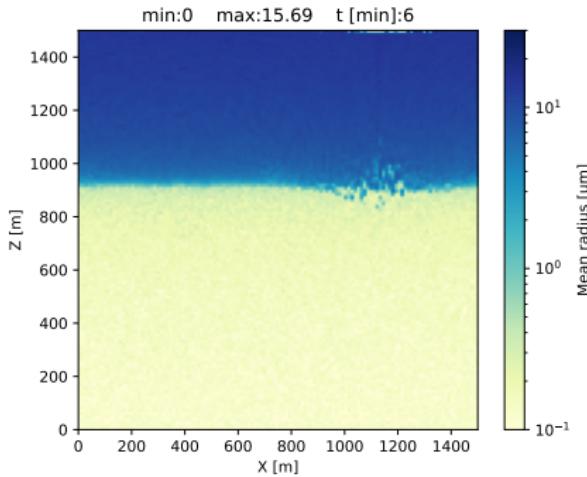
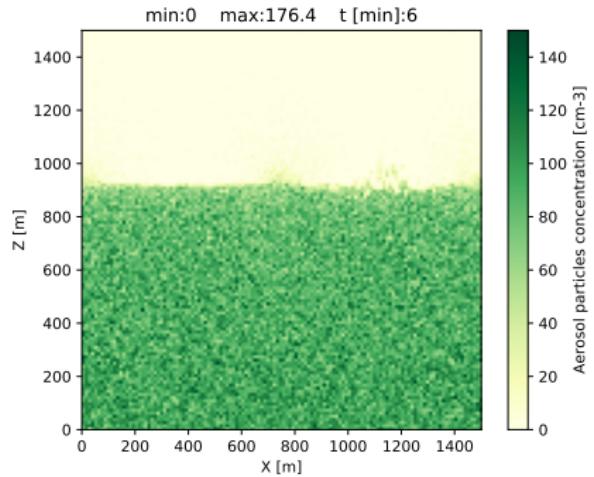
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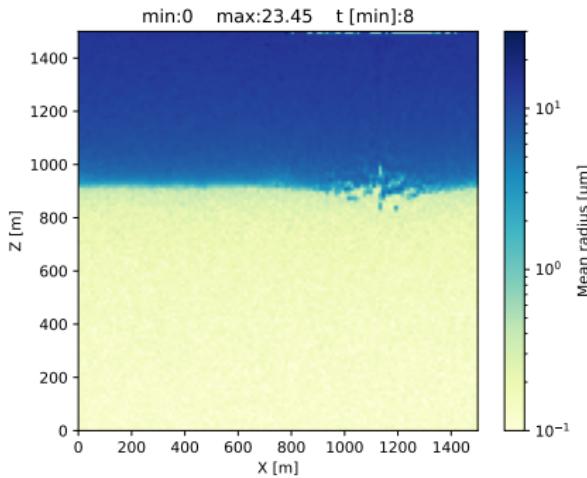
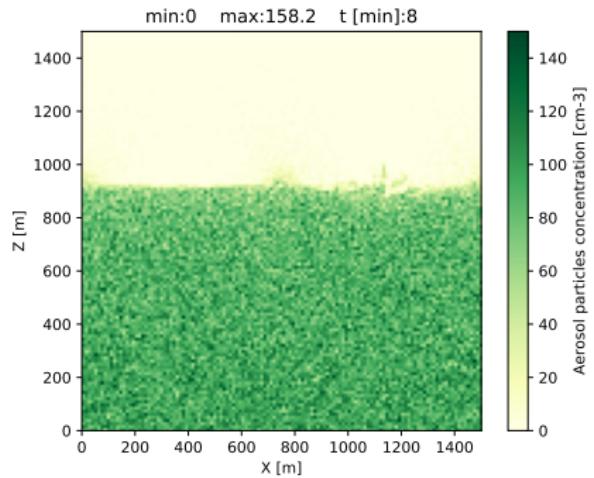
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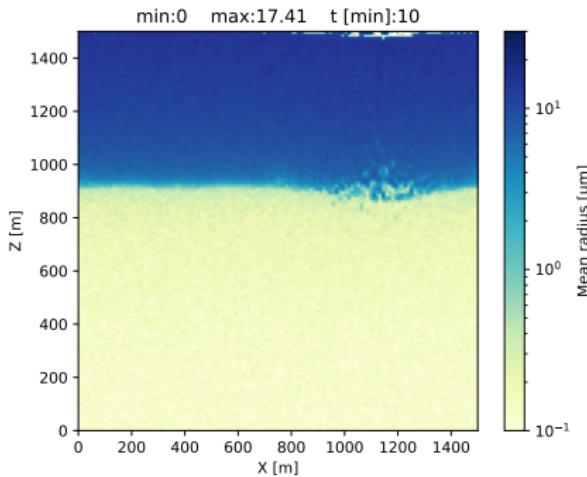
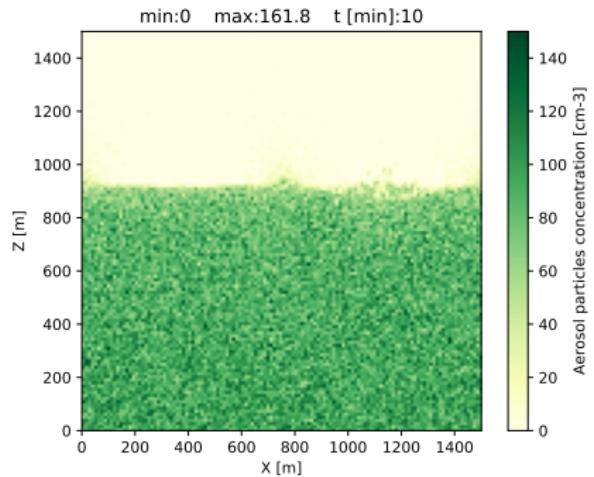
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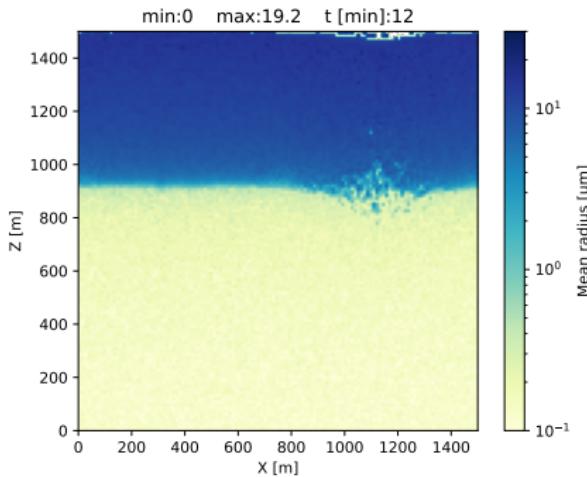
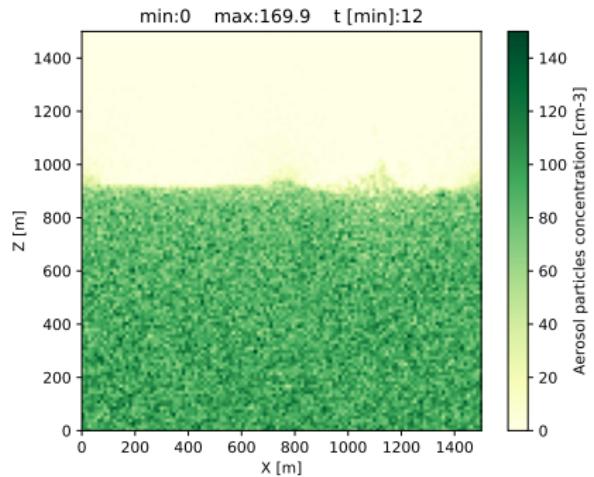
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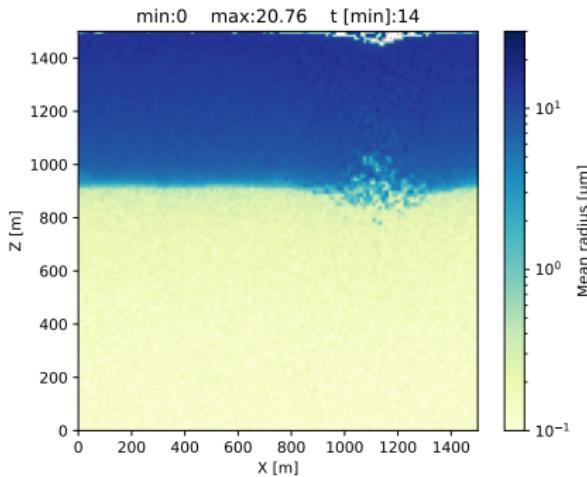
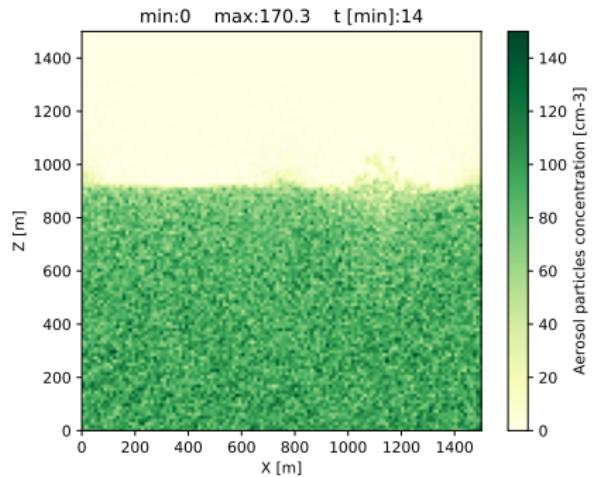
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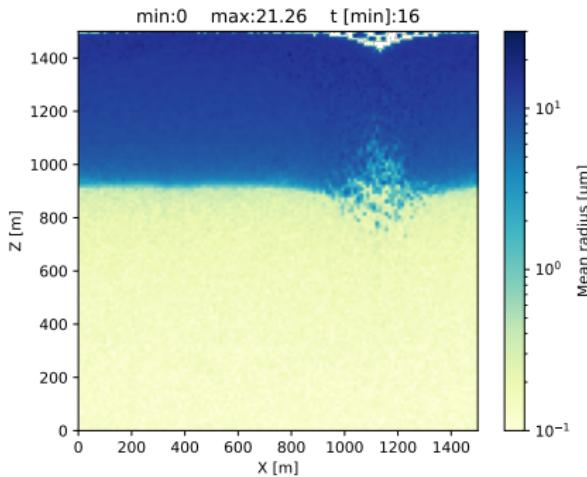
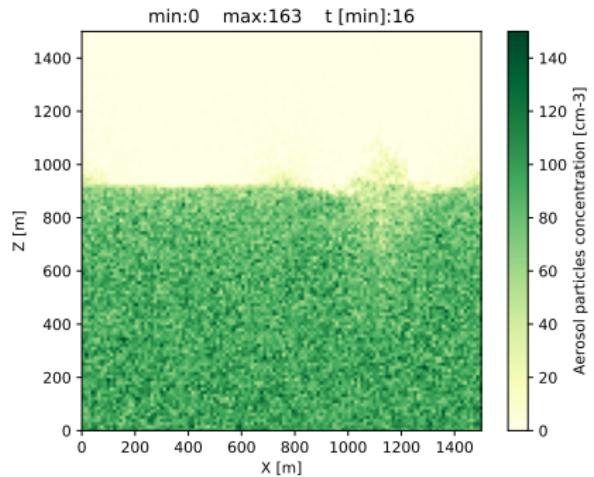
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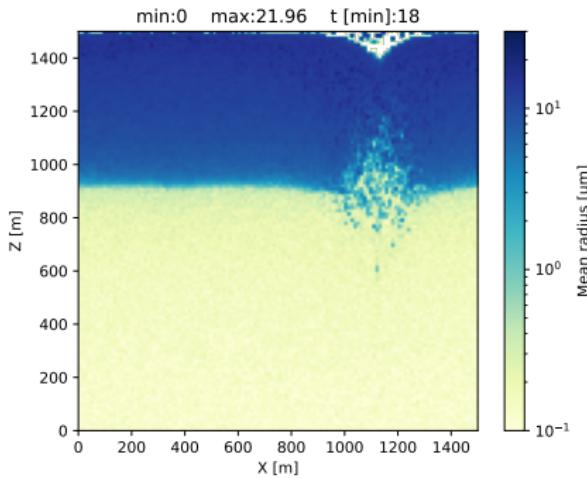
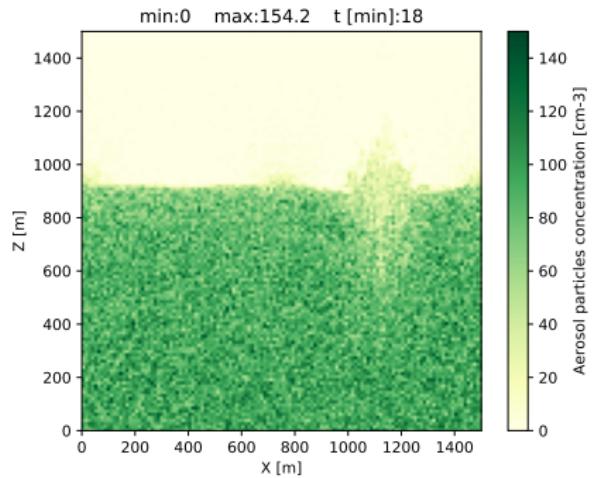
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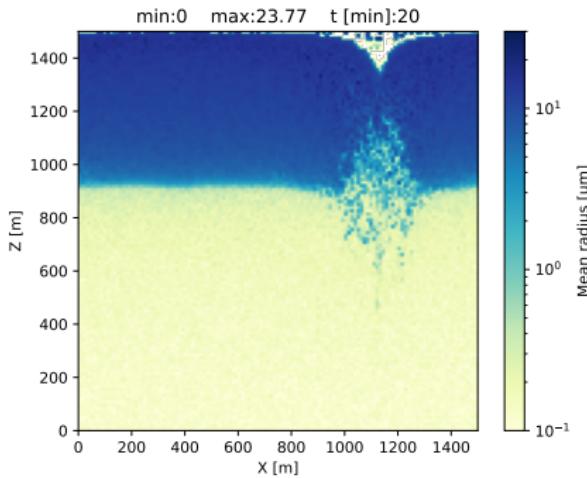
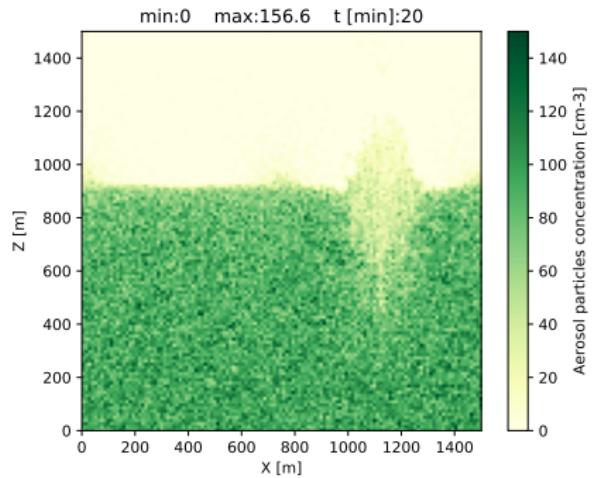
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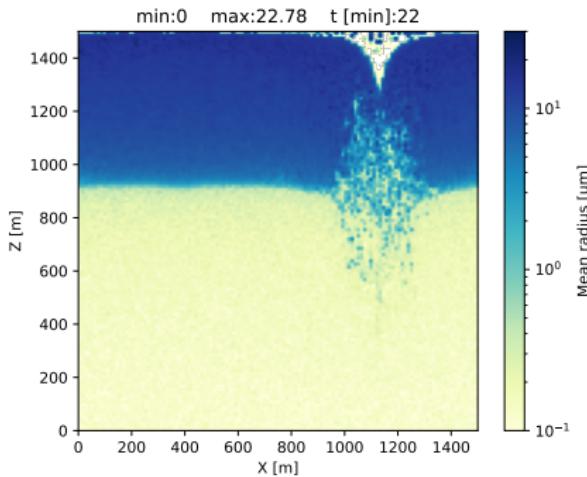
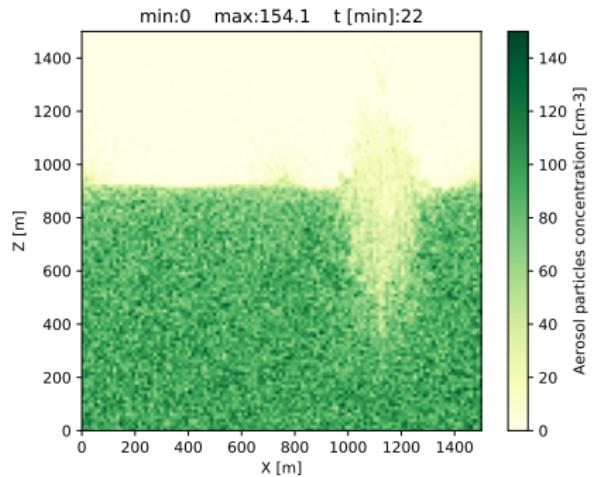
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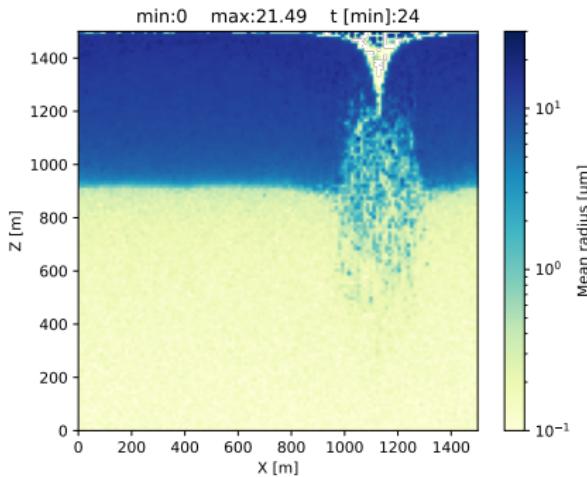
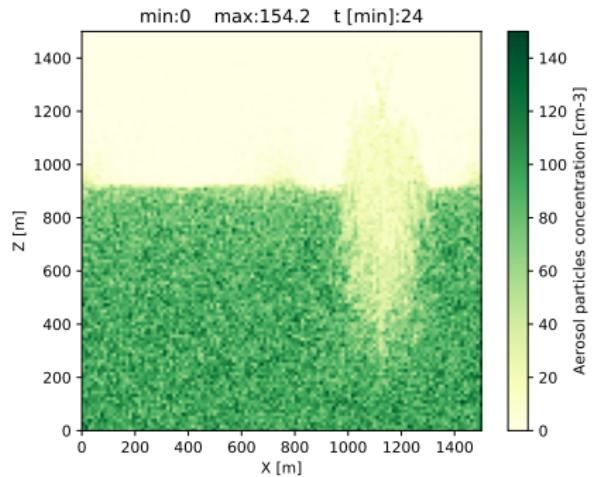
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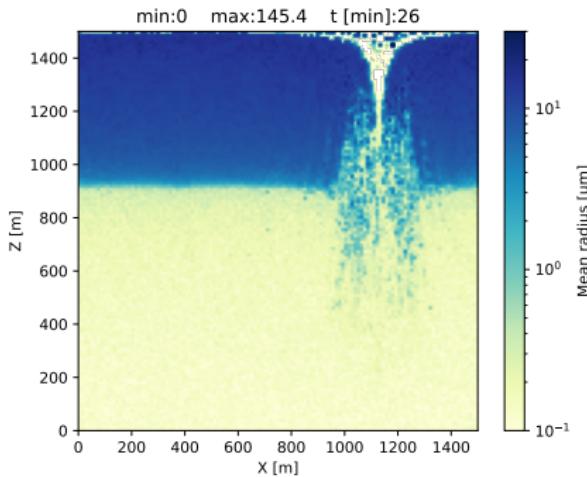
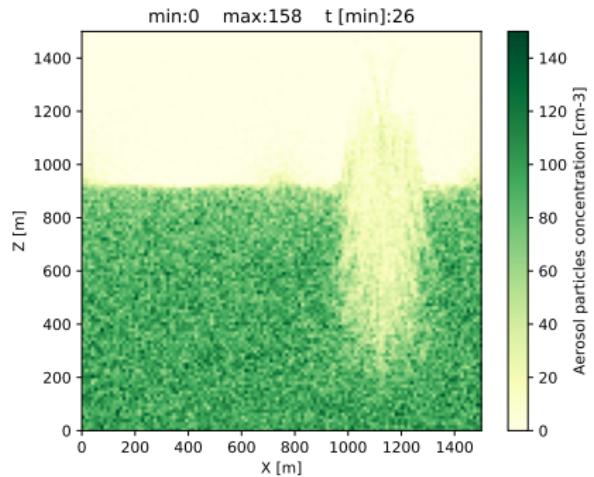
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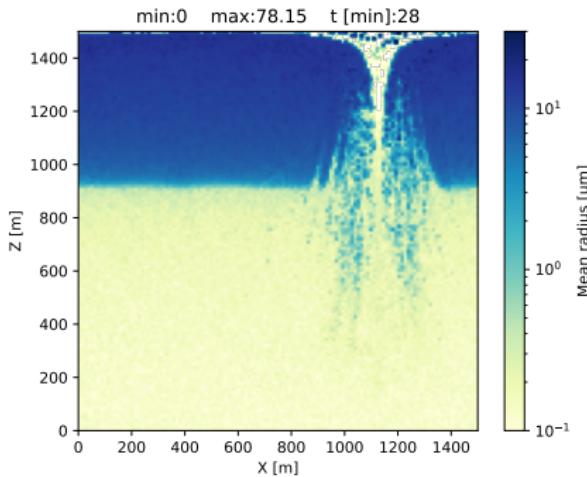
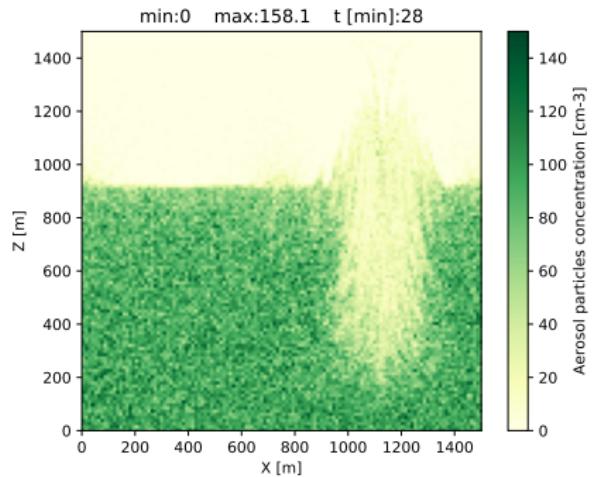
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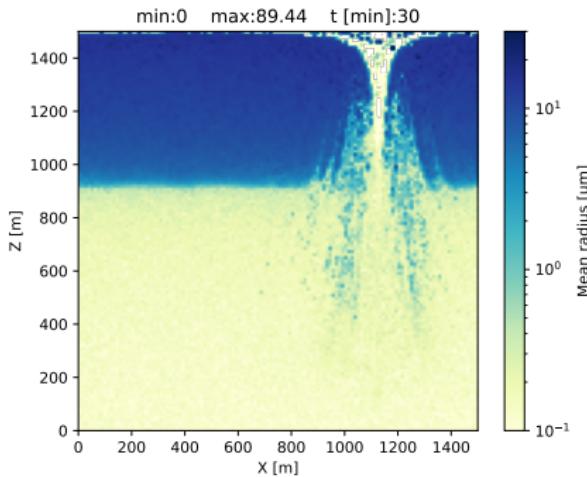
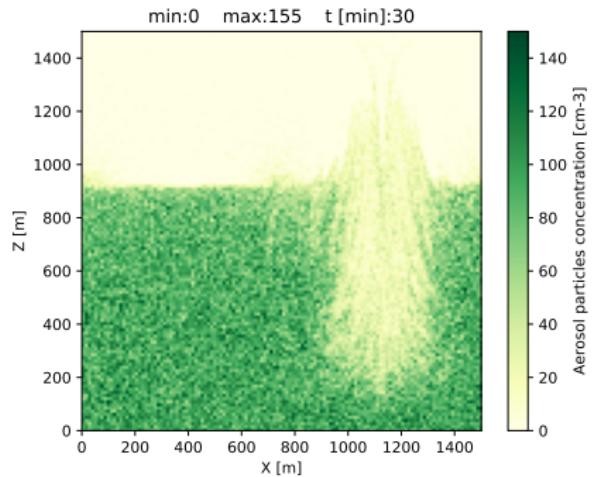
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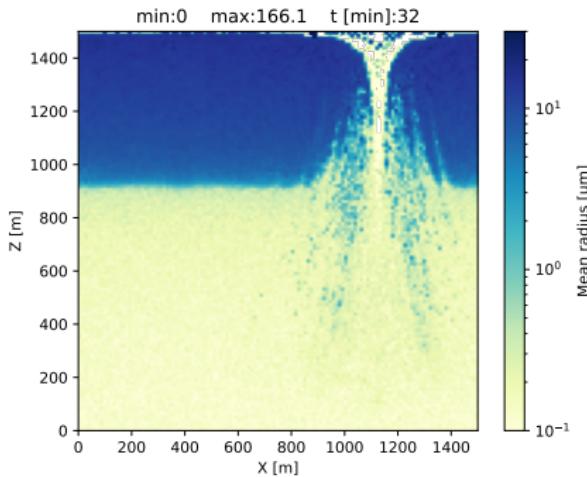
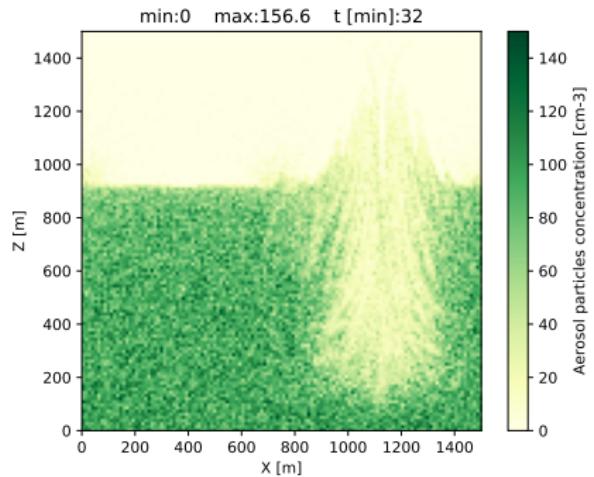
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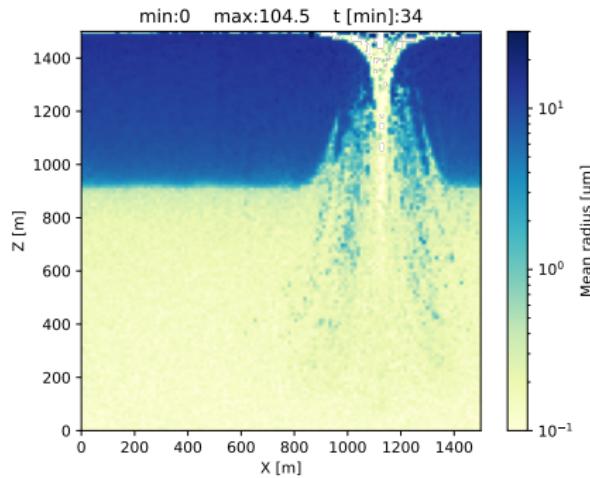
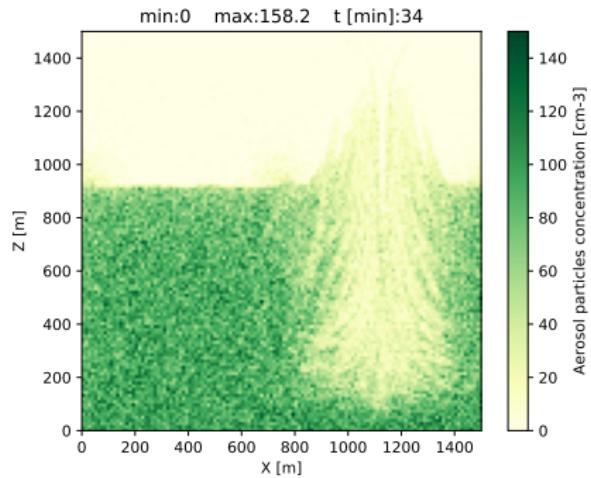
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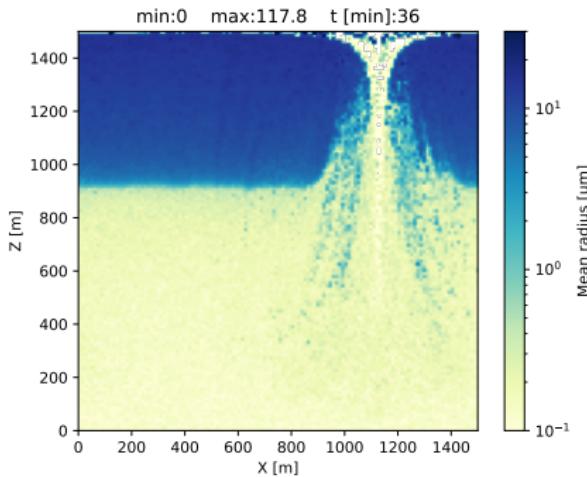
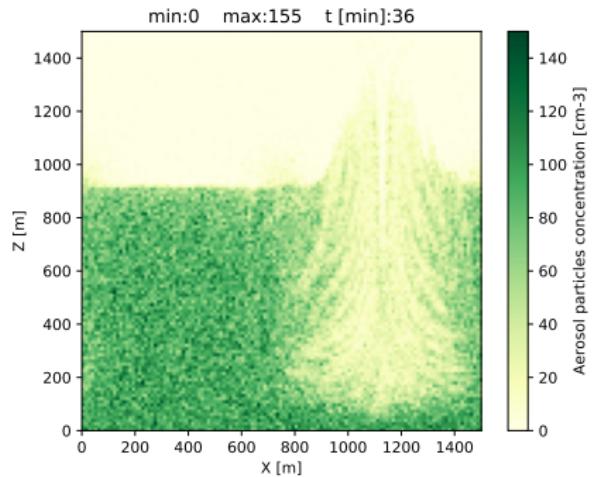
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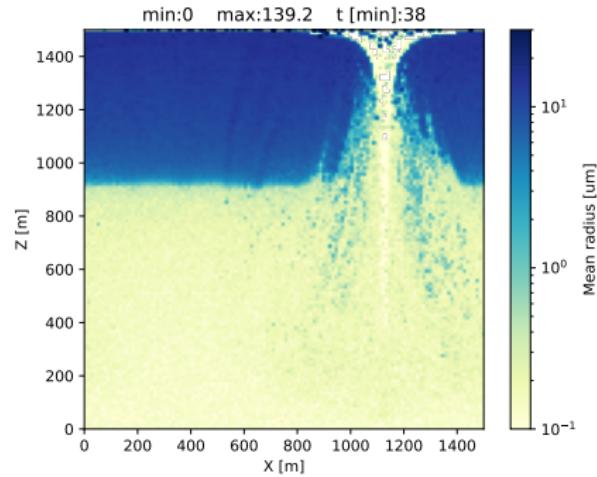
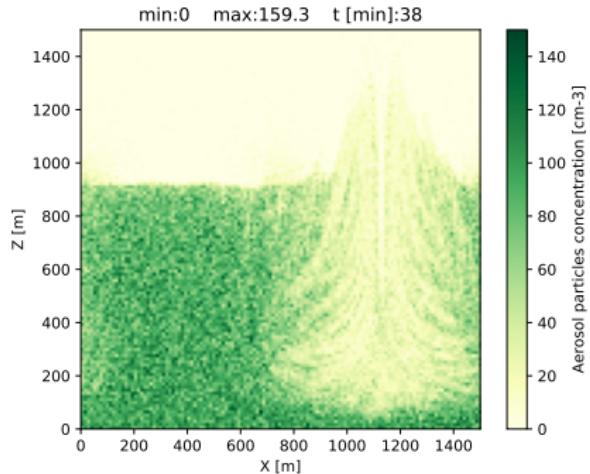
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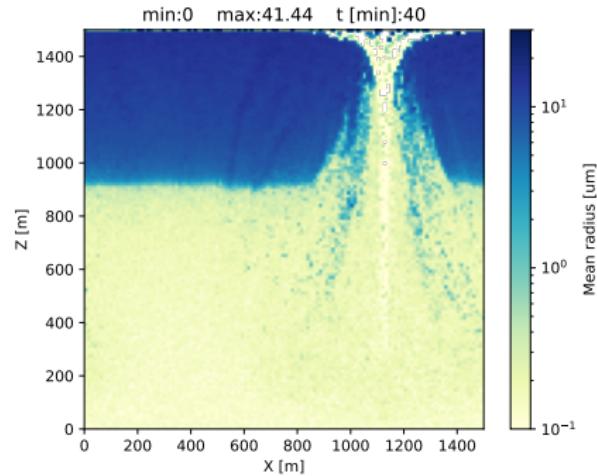
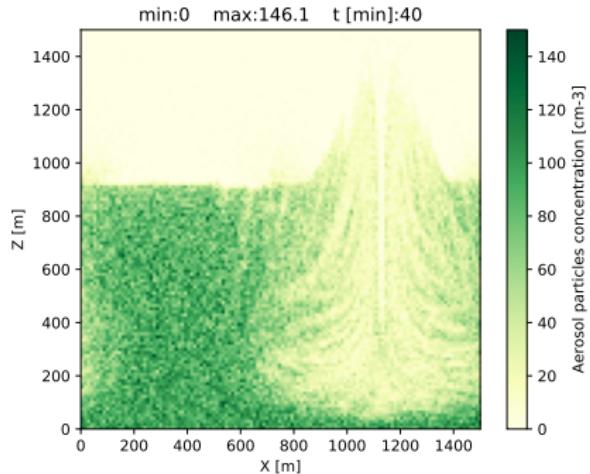
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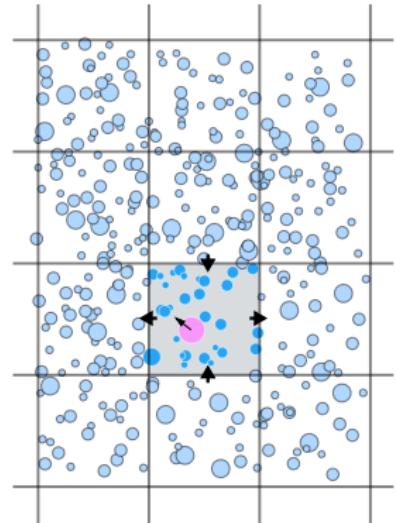
## Modeled processes

- ▶ Condensation - cloud droplet condensational growth
- ▶ Advection and Sedimentation - transport of droplets due to air flow and gravity
- ▶ Coalescence - cloud droplet collisional growth

# Cloud droplet condensational growth

# Thermodynamic variables

- $q$  mixing ratio of water vapor (ratio of the vapor density to the dry-air density),
- $\theta$  potential temperature (temperature that the air would attain if adiabatically brought to a reference pressure of 1000 hPa),
- $\rho_d$  dry-air density,



# Droplet growth law

Approximation of the two equations of diffusion (heat and vapor) with a single one:

$$\dot{s} = \frac{ds}{dr} \dot{r} = \frac{ds}{dr} \frac{1}{r} \frac{(RH(q, \theta, \rho_d)) - \frac{a}{r} + \frac{b}{r^3}}{F(q, \theta, \rho_d)} \quad (1)$$

$r$  - radius of droplet,  $s = \log(\frac{4}{3}\pi r^3)$

$RH$  - relative humidity

$a, b$  - parameters set according to the kappa-Köhler parameterization of hygroscopicity

$F^{-1}$  - effective diffusion coefficient

## Evolution of the environment (in each cell)

$$\begin{bmatrix} \dot{s}_{[i]} \\ \vdots \\ \dot{\rho}_d \\ \dot{q} \\ \dot{\theta} \end{bmatrix} = \begin{bmatrix} \dot{s}(s_{[i]}, \theta, q, \rho_d) \\ \vdots \\ 0 \\ \dot{q}_{cond} + \dot{q}_{env} \\ \dot{\theta}_{cond} + \dot{\theta}_{env} \end{bmatrix}$$

$$v_{[i]} = e^{s_{[i]}}$$

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$$\dot{q}_{cond}(x, z) = -\frac{\rho_I}{\rho_d} \frac{1}{\Delta V} \sum_i \xi_{[i]} \frac{dv_{[i]}}{dt}$$

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$$\dot{q}_{env}(x, z) = -\rho_d^{-1} \nabla \cdot (\vec{u} \rho_d q_v)$$

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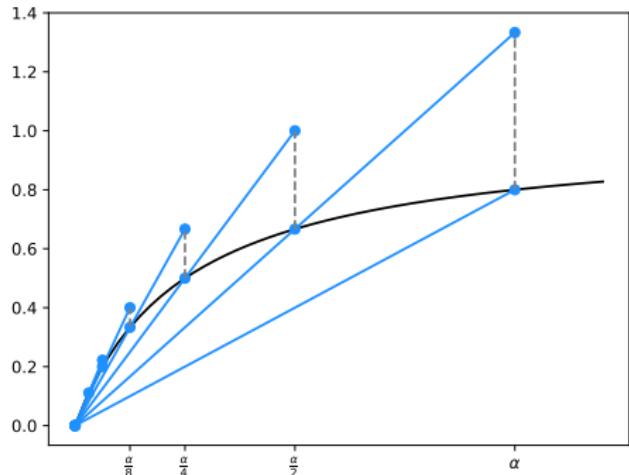
## Adaptive time step (proposed in PySDM)

In each major time step  $n$ , the number of time substeps is adjusted iteratively searching for such  $m \in \mathbb{N}$ , and as a consequence  $\alpha = \frac{1}{2^m}$ , for which the following condition holds:

$$\left| \underbrace{\left( \theta^{n+\frac{1}{2\alpha}} \Big|_{2\alpha} - \theta^n \right) - 2 \left( \theta^{n+\frac{1}{\alpha}} \Big|_{\alpha} - \theta^n \right)}_{\Delta\theta|_{2\alpha} - 2\Delta\theta|_{\alpha}} \right| < r_\theta |\theta^n| \quad (2)$$

where  $r_\theta$  is the relative tolerance. Note that if only  $\theta$  is differentiable in the limit of  $m \rightarrow \infty$ , the left-hand side of ineq. (2)  $|\Delta\theta|_{2\alpha} - 2\Delta\theta|_{\alpha}| \rightarrow 0$  assuring convergence.

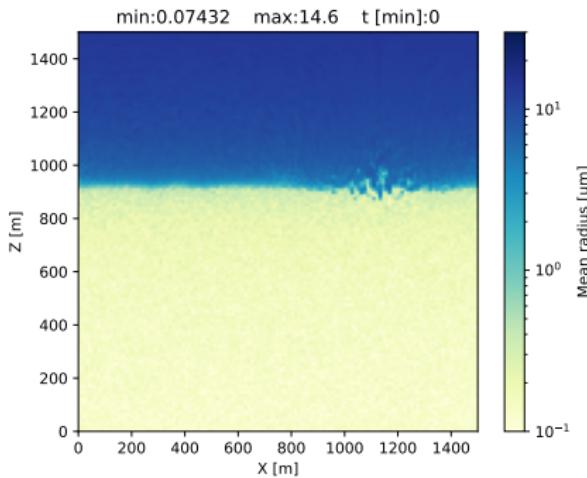
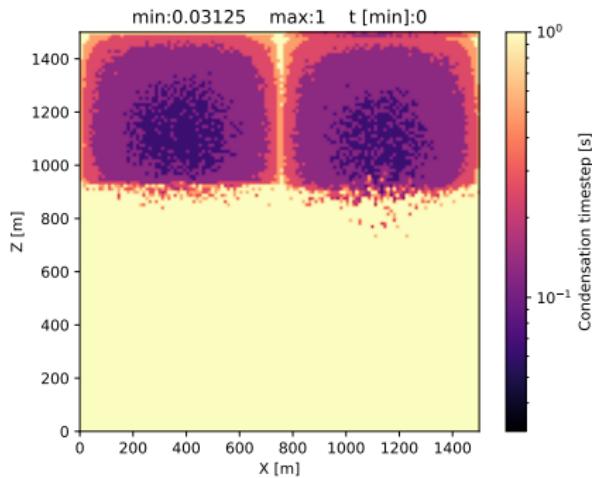
# Adaptive time step (proposed in PySDM)



- o no additional memory is required
- o condensation step adapted:
  - once per major time step
  - in each cell independently

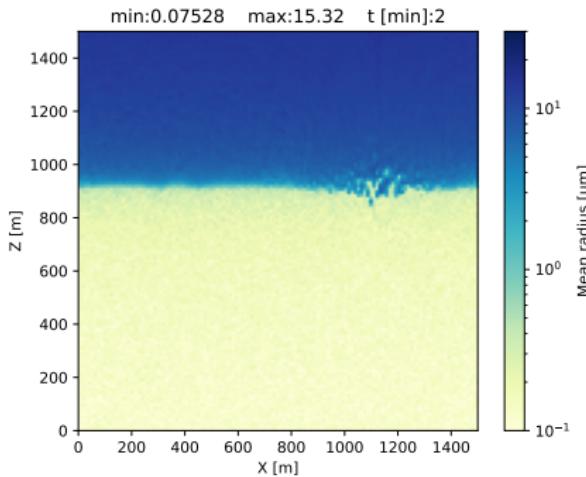
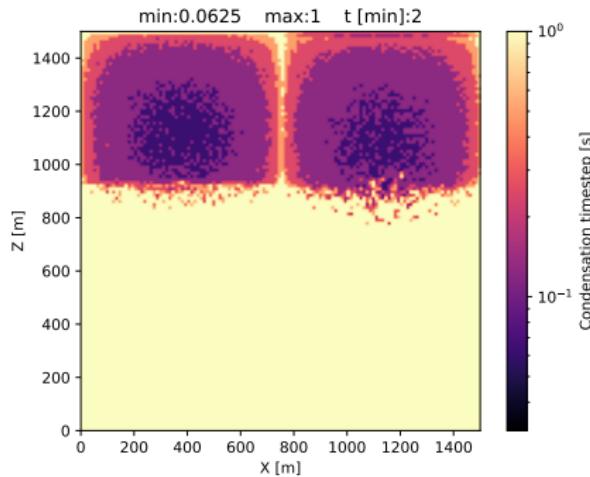
Conceptual view of inequality (2).

# Condensation solver adaptivity



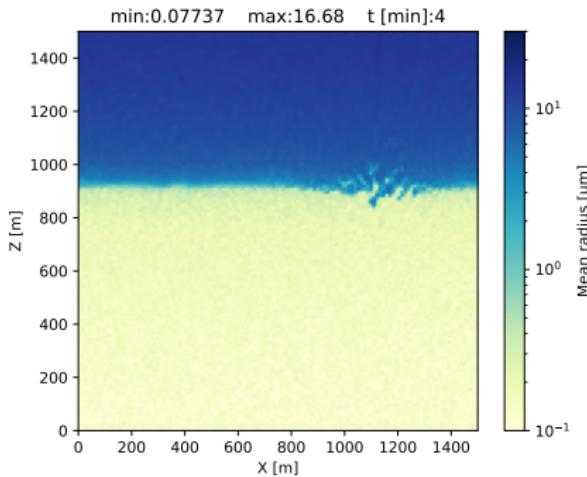
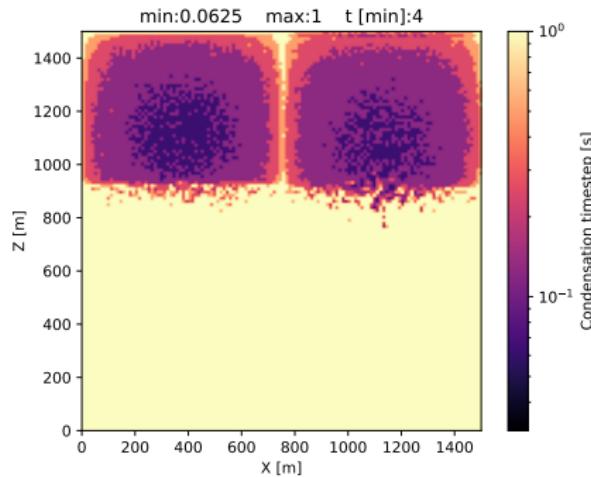
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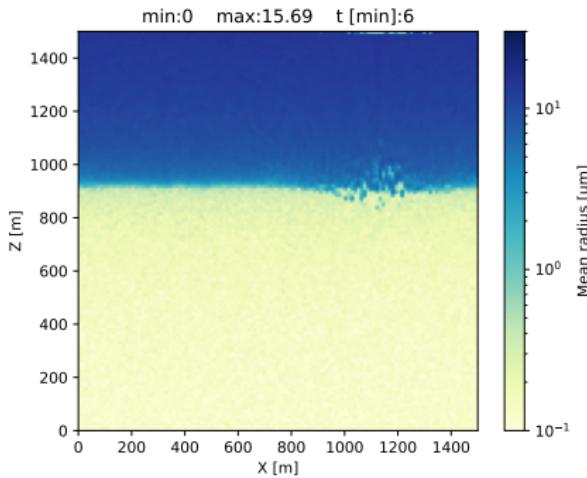
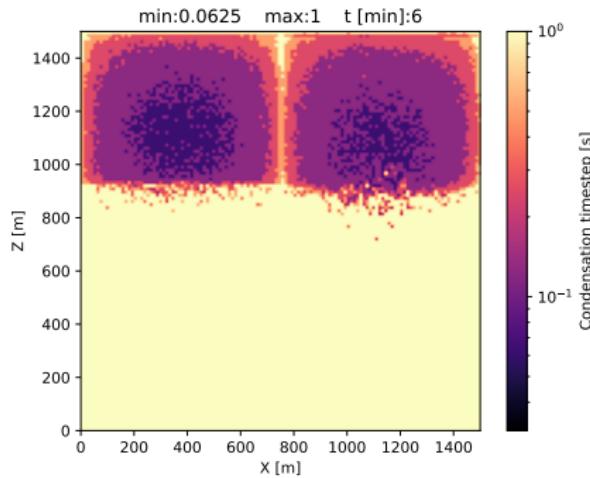
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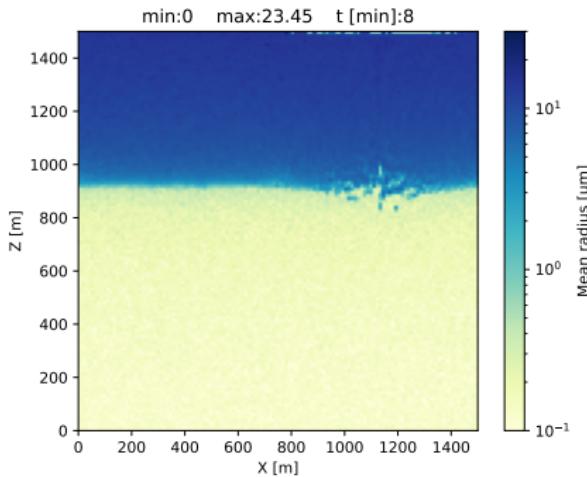
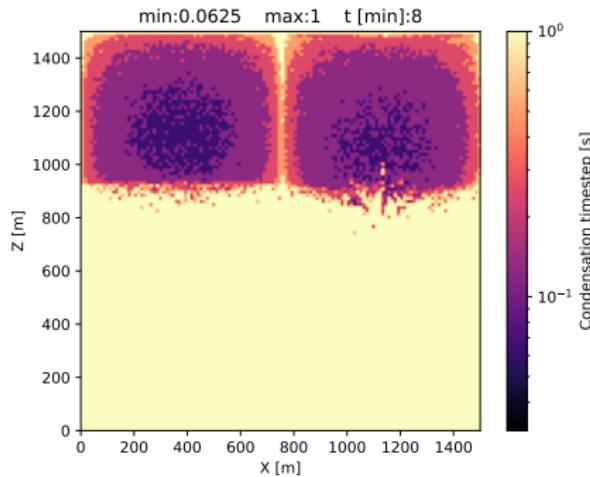
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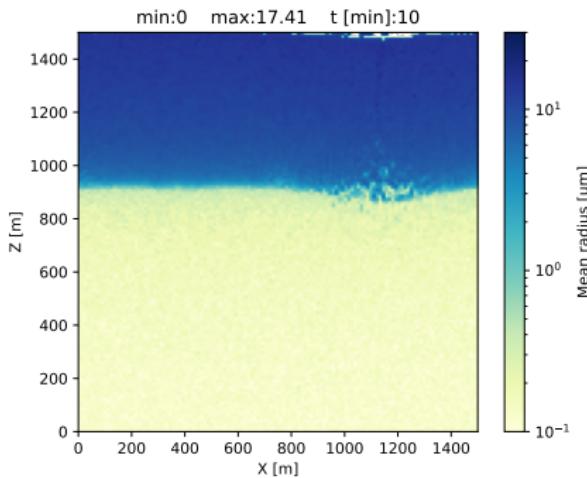
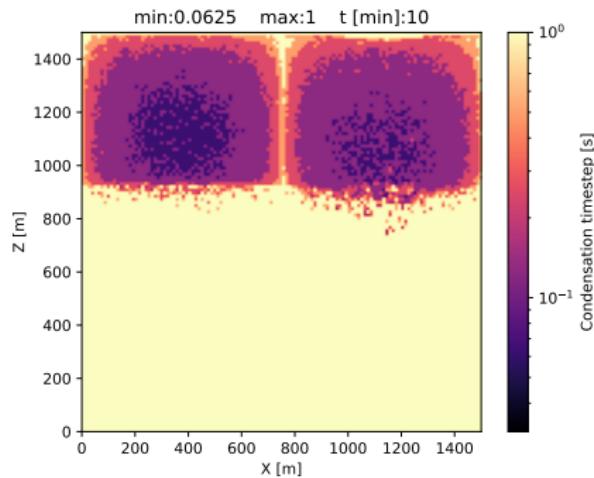
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Computational particles:  $2^{21}$

# Condensation solver adaptivity



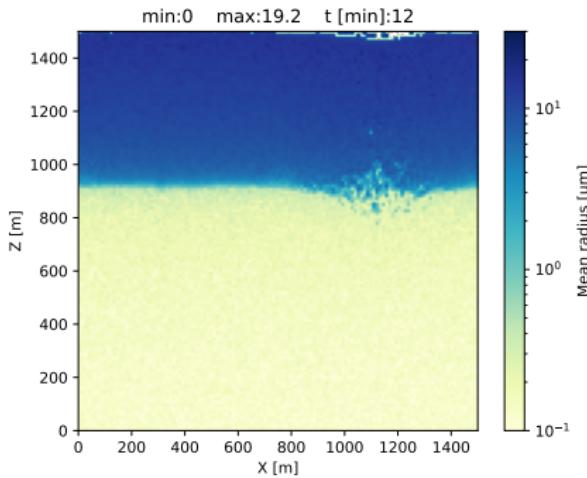
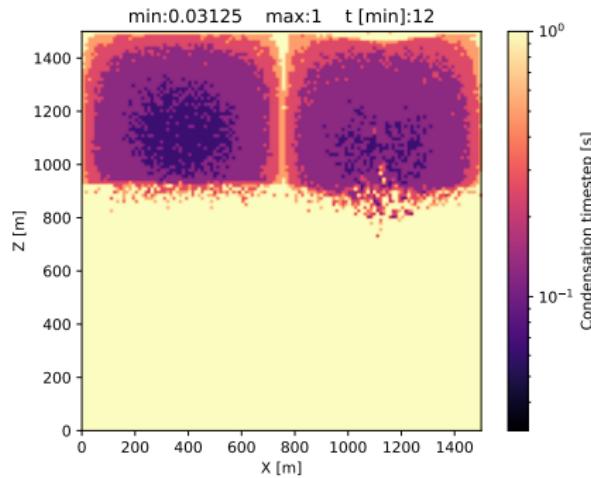
Computational grid: 128x128  
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# Condensation solver adaptivity



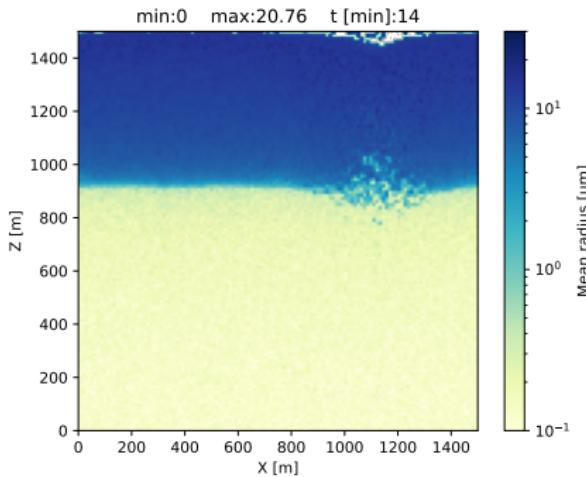
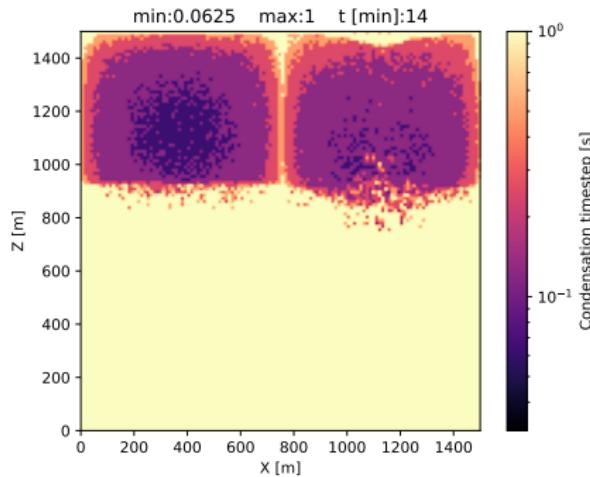
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# Condensation solver adaptivity



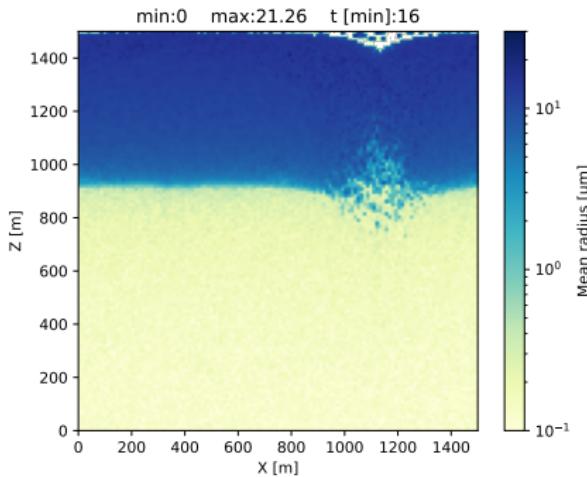
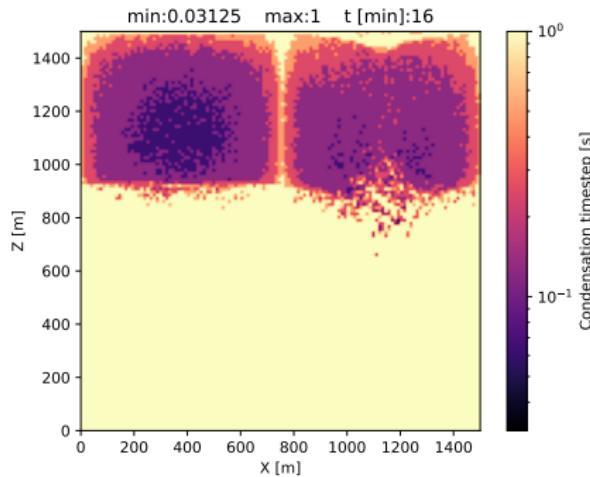
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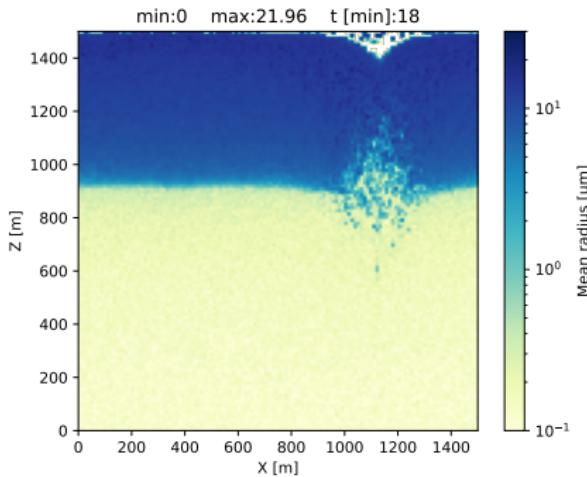
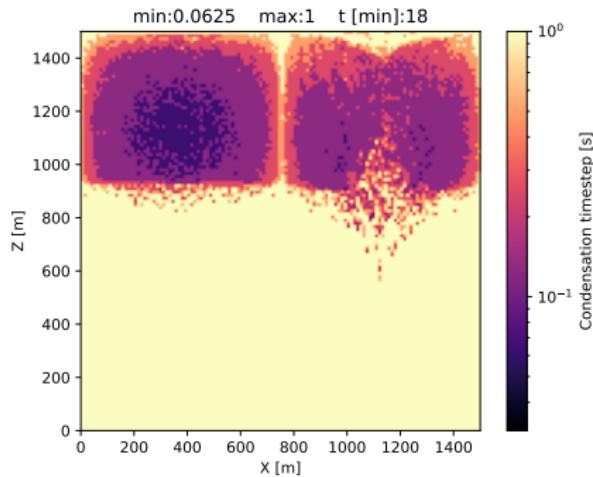
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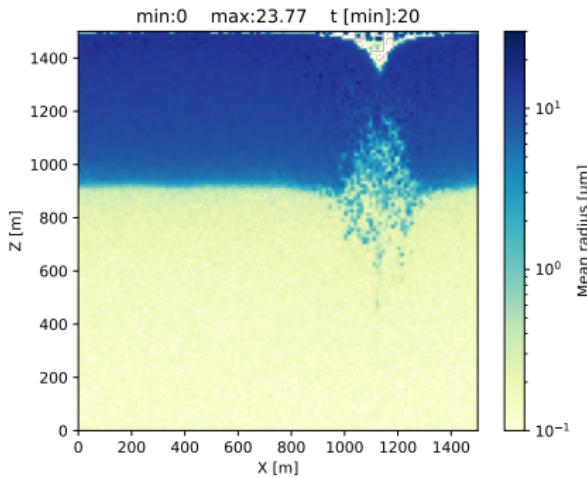
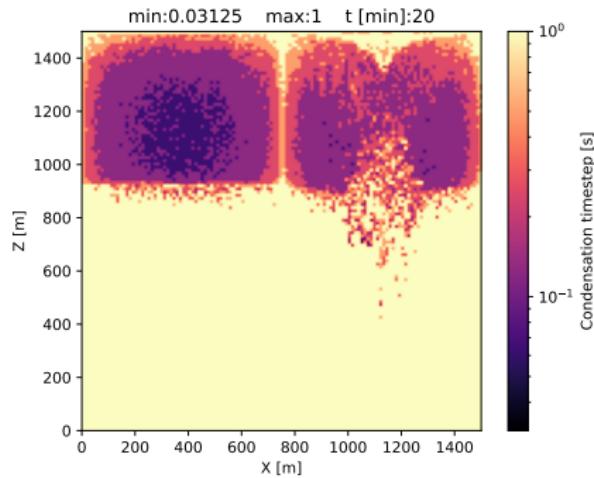
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# Condensation solver adaptivity



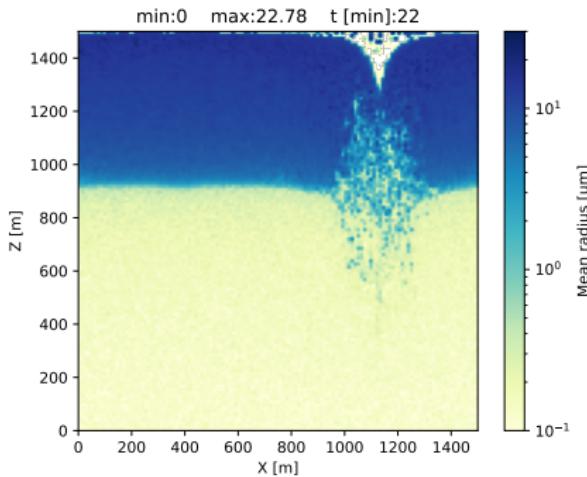
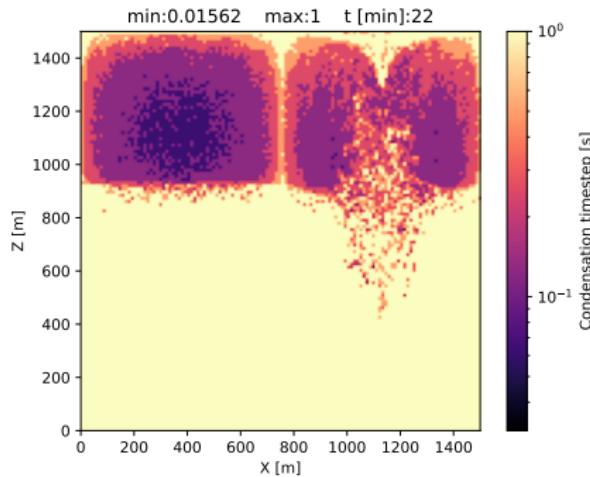
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Computational particles:  $2^{21}$

# Condensation solver adaptivity



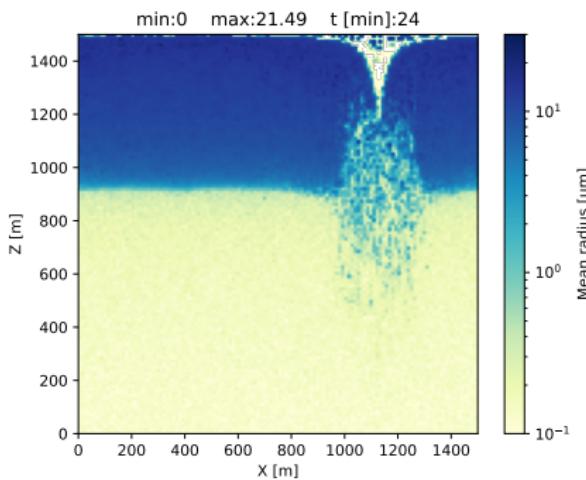
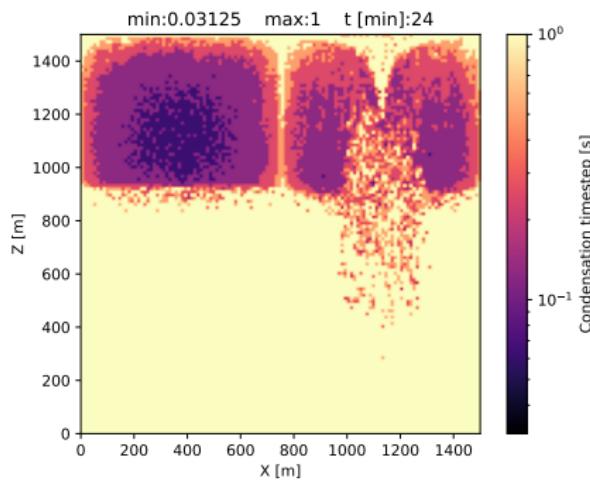
Computational grid: 128x128  
Computational particles:  $2^{21}$

# Condensation solver adaptivity



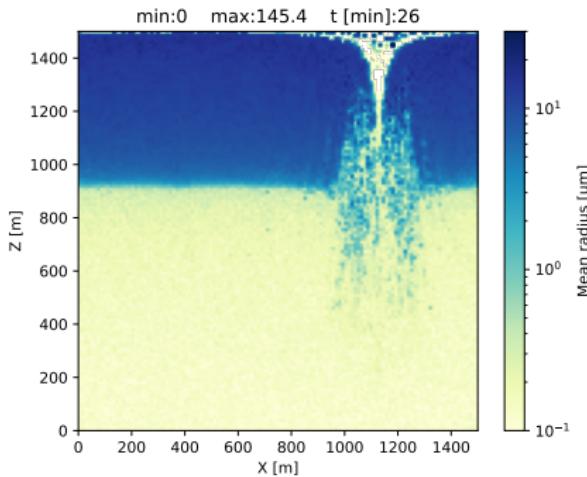
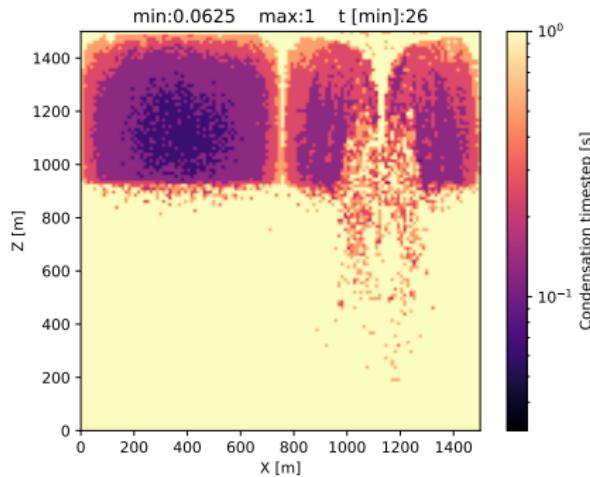
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# Condensation solver adaptivity



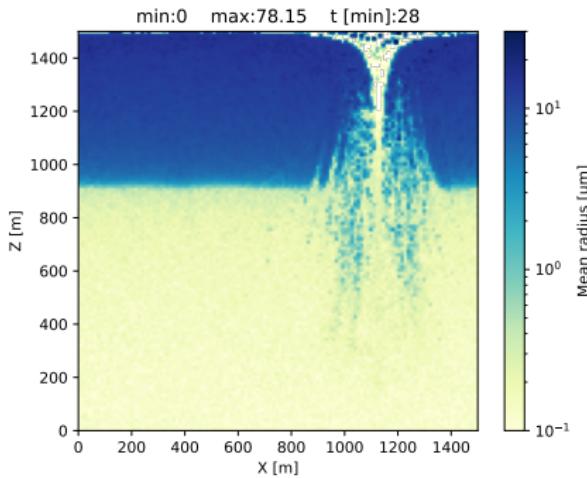
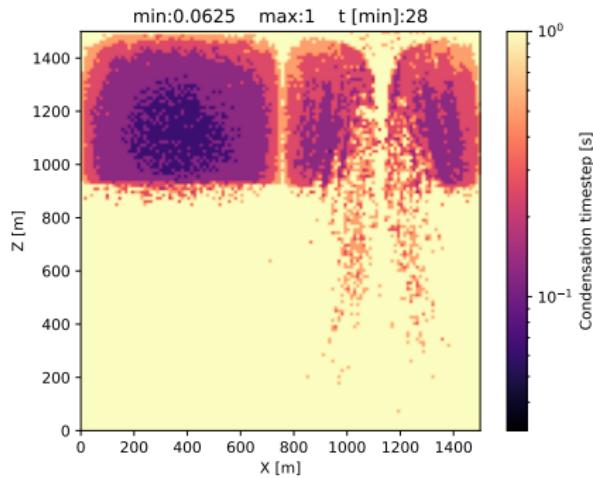
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# Condensation solver adaptivity



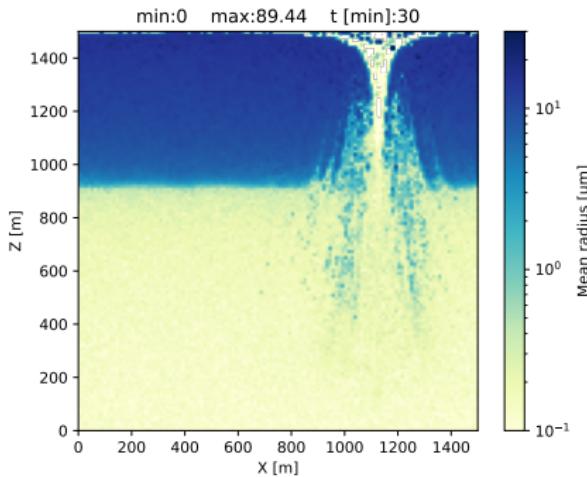
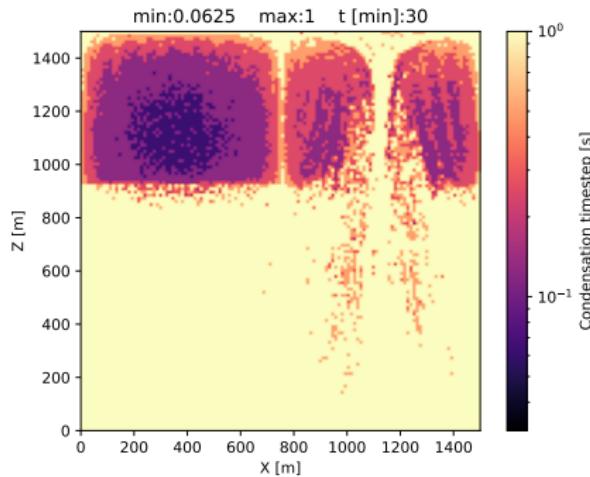
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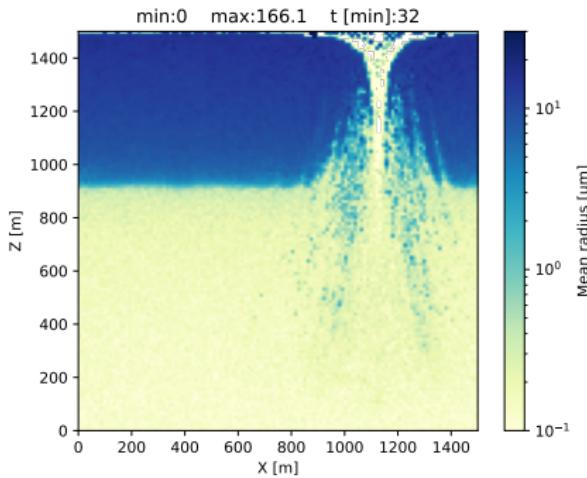
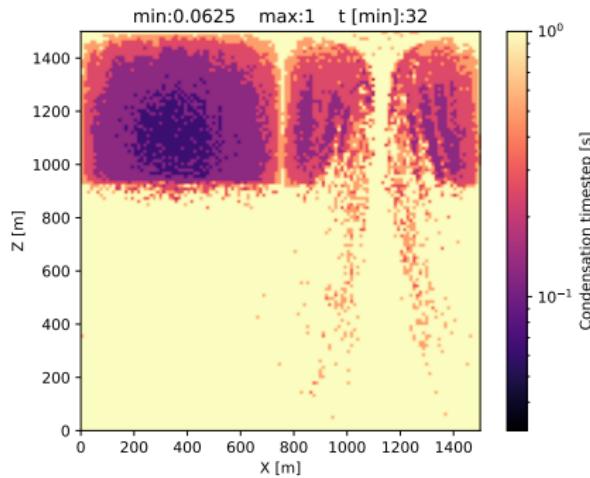
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# Condensation solver adaptivity



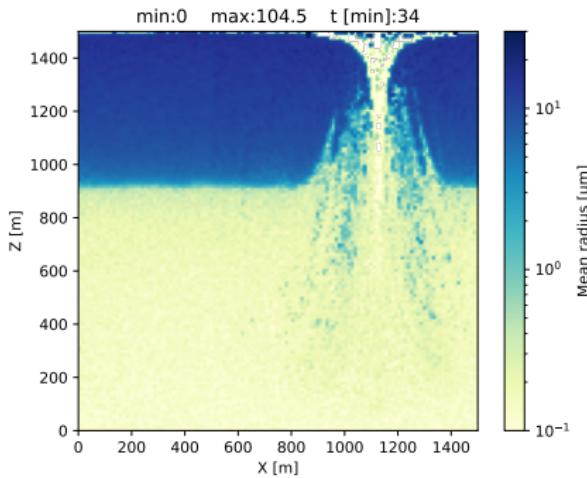
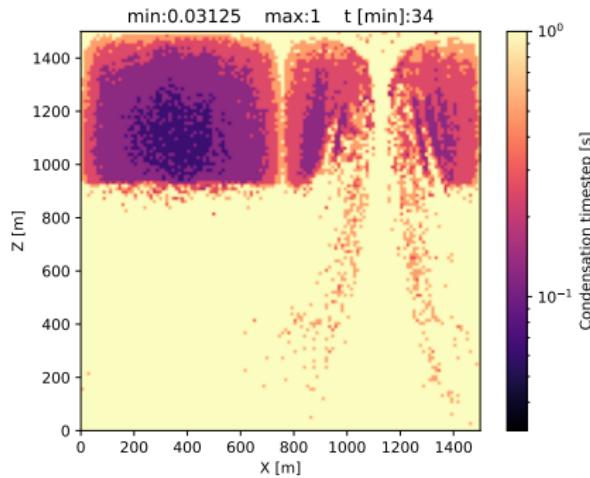
Computational grid: 128x128  
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# Condensation solver adaptivity



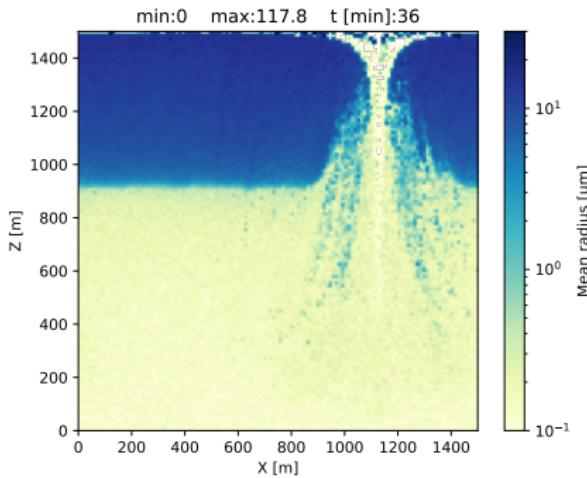
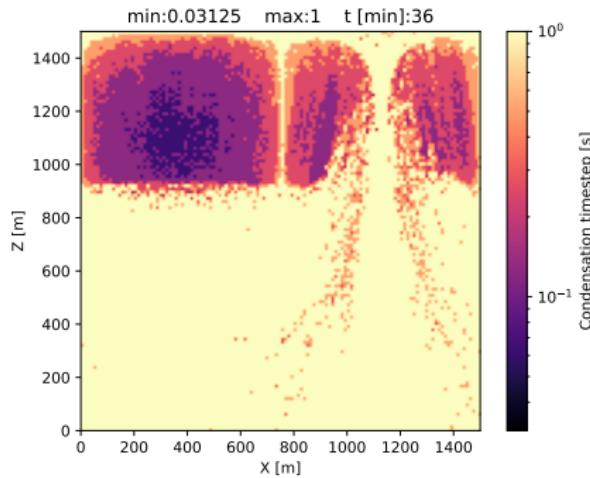
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# Condensation solver adaptivity



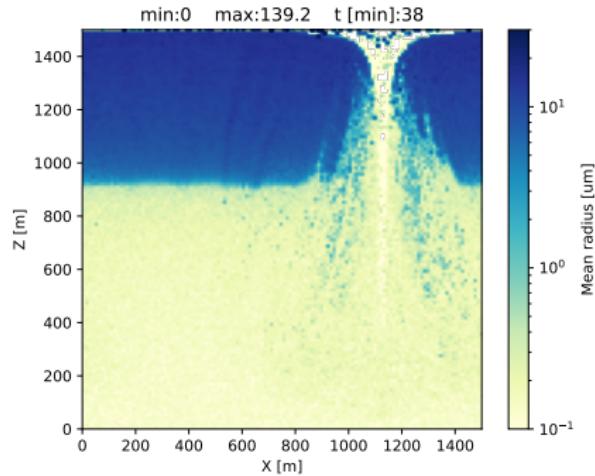
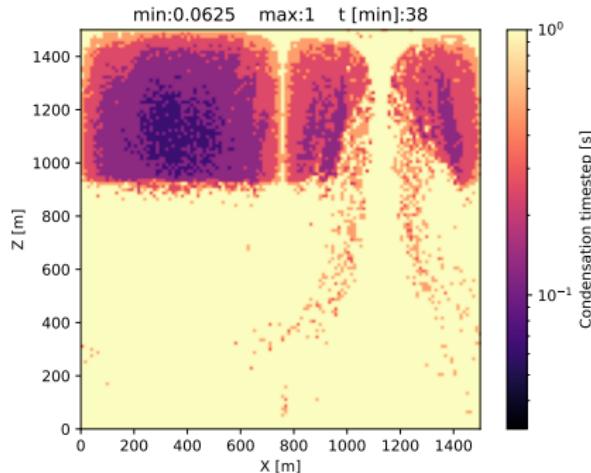
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# Condensation solver adaptivity



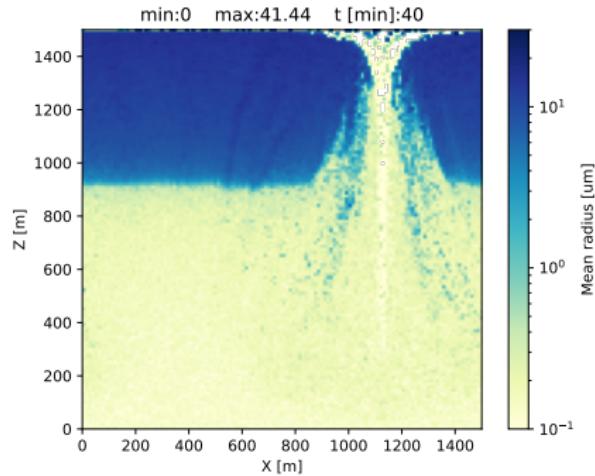
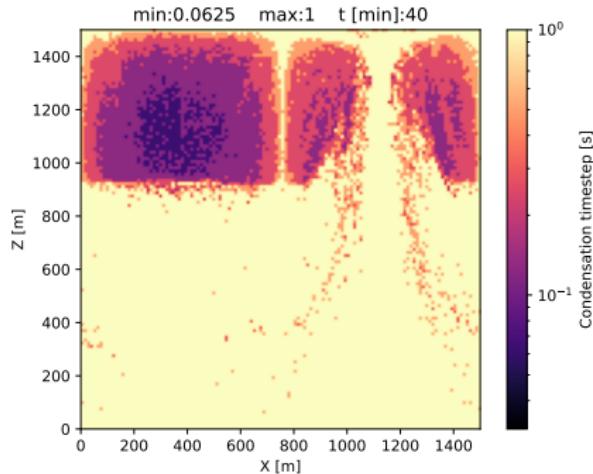
Computational grid: 128x128  
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# Condensation solver adaptivity



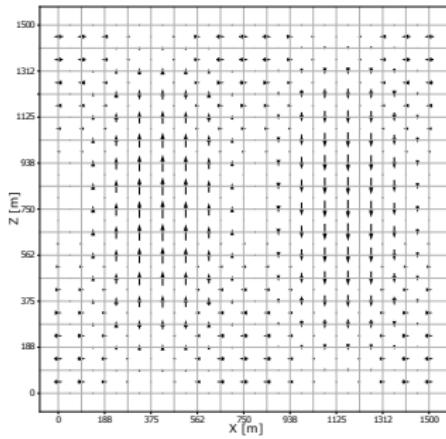
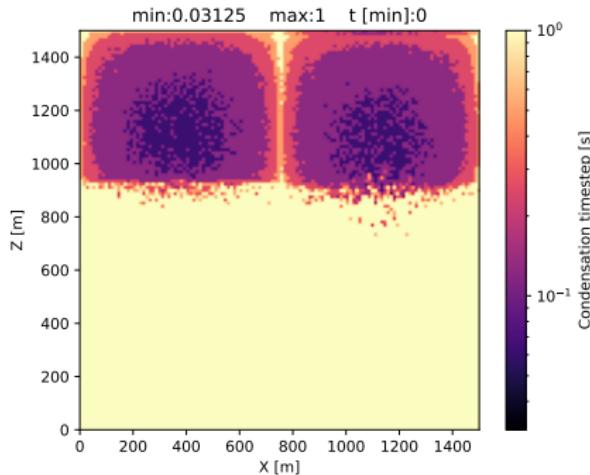
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# Condensation solver adaptivity



Computational grid: 128x128  
Computational particles:  $2^{21}$

# Condensation solver adaptivity



Computational grid: 128x128  
Computational particles:  $2^{21}$

# Cloud droplet collisional growth

# Cloud droplet collisional growth

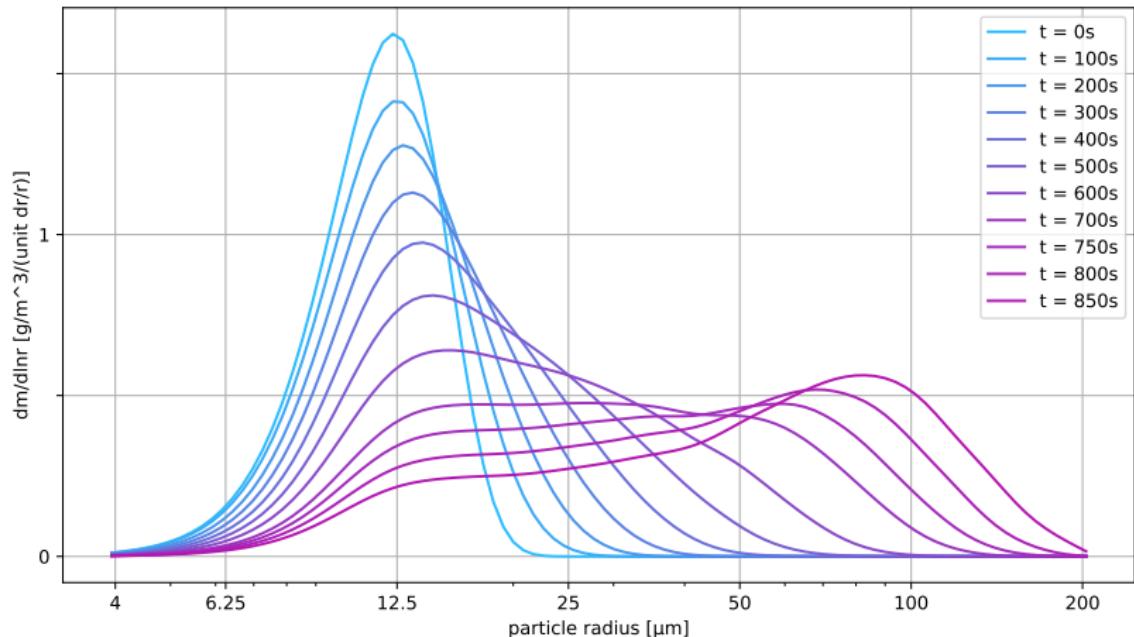
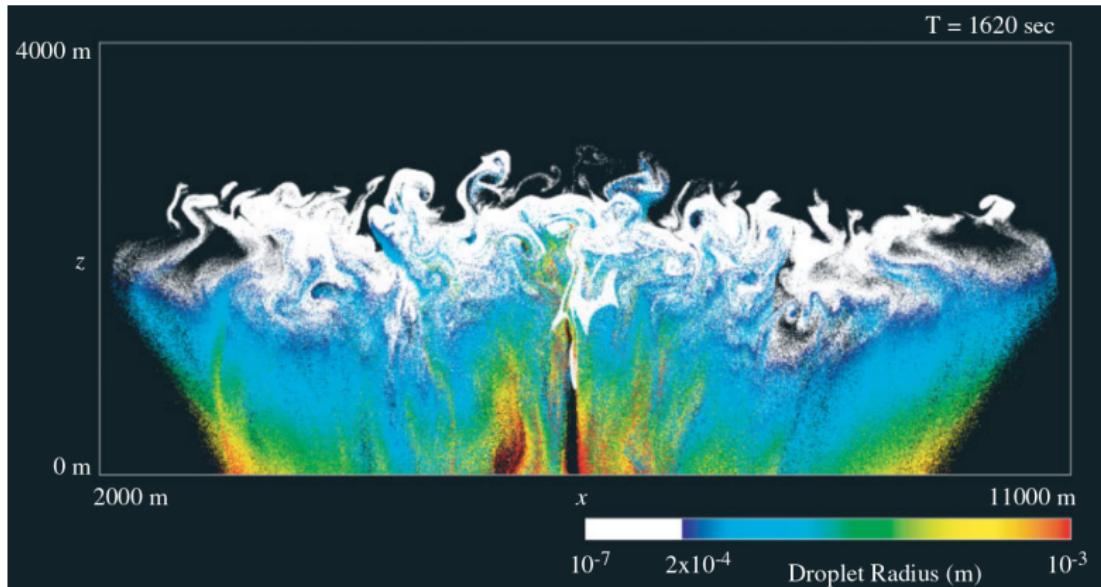


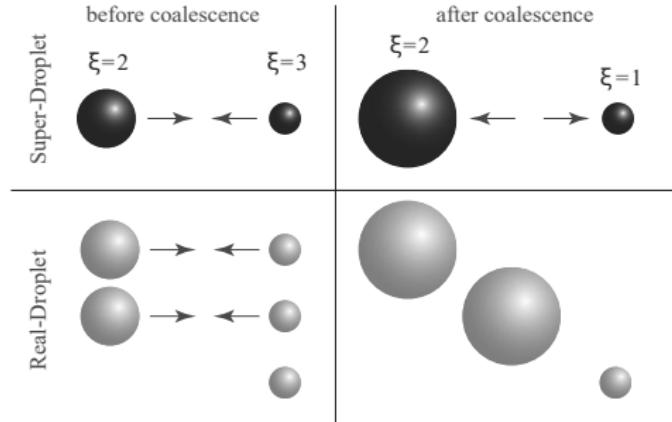
Fig. 5 from Berry 1967 reproduced by PySDM.

# Probabilistic particle-based simulations



Super-droplet simulation of a shallow convective cloud  
(figure: Shima et al. 2009, QJRMS)

# Super-Droplet Method (SDM)



Conceptual view of collision in SDM.  
(figure: Shima et al. 2009, QJRMS)

$$\gamma = \left[ a(v_{[j]}, v_{[k]}) \frac{\Delta t}{V} \max\{\xi_{[j]}, \xi_{[k]}\} \frac{n_{sd}(n_{sd}-1)/2}{n_{sd}/2} - \phi_\gamma \right] \quad (3)$$

$$\phi_\gamma \sim Uniform[0, 1)$$

assuming  $\xi_{[j]} > \xi_{[k]}$  and  $\tilde{\gamma} = \min\{\gamma, \lfloor \xi_{[j]}/\xi_{[k]} \rfloor\}$

# Super-Droplet Method (SDM)

1.  $\xi_{[j]} - \tilde{\gamma}\xi_{[k]} > 0$

$$\hat{\xi}_{[j]} = \xi_{[j]} - \tilde{\gamma}\xi_{[k]}$$

$$\hat{A}_{[j]}^{ex} = A_{[j]}^{ex}$$

$$\hat{A}_{[j]}^{in} = A_{[j]}^{in}$$

$$\hat{\xi}_{[k]} = \xi_{[k]}$$

$$\hat{A}_{[k]}^{ex} = A_{[k]}^{ex} + \tilde{\gamma}A_{[j]}^{ex}$$

$$\hat{A}_{[k]}^{in} = \frac{A_{[k]}^{in}v_{[k]} + \tilde{\gamma}A_{[j]}^{in}v_{[j]}}{v_{[k]} + \tilde{\gamma}v_{[j]}}$$

2.  $\xi_{[j]} - \tilde{\gamma}\xi_{[k]} = 0$

$$\hat{\xi}_{[j]} = \lfloor \xi_{[k]} / 2 \rfloor$$

$$\hat{A}_{[j]}^{ex} = \hat{A}_{[k]}^{ex}$$

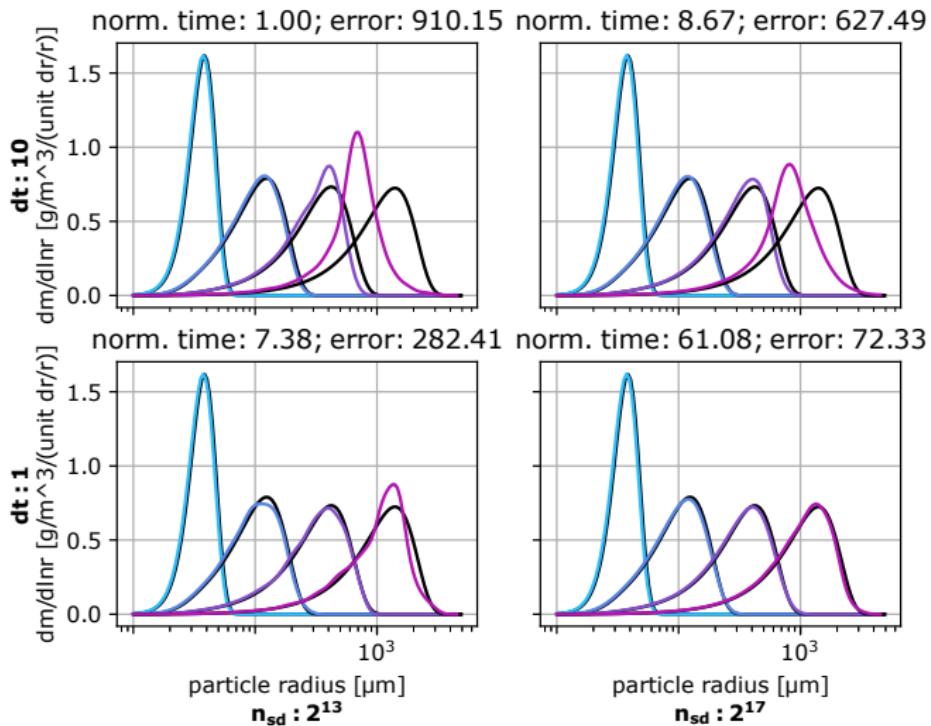
$$\hat{A}_{[j]}^{in} = \hat{A}_{[k]}^{in}$$

$$\hat{\xi}_{[k]} = \xi_{[k]} - \lfloor \xi_{[k]} / 2 \rfloor$$

$$\hat{A}_{[k]}^{ex} = A_{[k]}^{ex} + \tilde{\gamma}A_{[j]}^{ex}$$

$$\hat{A}_{[k]}^{in} = \frac{A_{[k]}^{in}v_{[k]} + \tilde{\gamma}A_{[j]}^{in}v_{[j]}}{v_{[k]} + \tilde{\gamma}v_{[j]}}$$

# SDM: sensitivity to time step



## SDM: adaptive time step (proposed in PySDM)

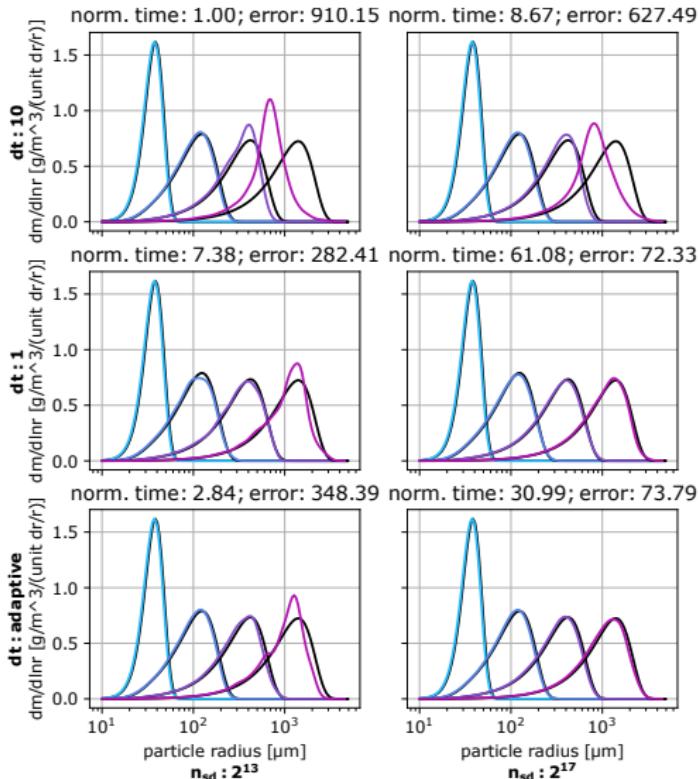
The aim of the proposed adaptivity scheme is to avoid situation when  $\gamma > \lfloor \xi_{[j]}/\xi_{[k]} \rfloor$  by adjusting the number of sub-steps  $k^{n+1}$  in next major time step based on the collision rates during current major time step:

$$k^{n+1} = \frac{\frac{1}{k^n} \sum_{s=0}^{k^n} w^{n_s} + \max_s \{w^{n_s}\}}{2} \quad (4)$$

$$w^{n_s} = \max_p \left\{ \left\lfloor k^n \gamma_p^{n_s} / \left\lfloor \frac{\xi_{[j]}^{n_s}}{\xi_{[k]}^{n_s}} \right\rfloor \right\rfloor \right\} \quad (5)$$

where  $p \in \{(j, k) : j, k \in [0, n_{sd}] \text{ and } j\text{-th and } k\text{-th super-droplets are a colliding pair}\}$ .

# SDM: adaptive time step (proposed in PySDM)



# PySDM

# technological stack and workflows

- Python [python.org](https://python.org)
- Numba [numba.pydata.org](https://numba.pydata.org)
- ThrustRTC [pypi.org/project/ThrustRTC](https://pypi.org/project/ThrustRTC)



# technological stack and workflows

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- Numba [numba.pydata.org](https://numba.pydata.org)
- ThrustRTC [pypi.org/project/ThrustRTC](https://pypi.org/project/ThrustRTC)
- GitHub & GitHub Actions [github.com](https://github.com)
- TravisCI [travis-ci.org](https://travis-ci.org)
- AppVeyor [appveyor.com](https://appveyor.com)



# technological stack and workflows

- ❖ Python [python.org](https://python.org)
- ❖ Numba [numba.pydata.org](https://numba.pydata.org)
- ❖ ThrustRTC [pypi.org/project/ThrustRTC](https://pypi.org/project/ThrustRTC)
- ❖ GitHub & GitHub Actions [github.com](https://github.com)
- ❖ TravisCI [travis-ci.org](https://travis-ci.org)
- ❖ AppVeyor [appveyor.com](https://appveyor.com)
- ❖ Jupyter [jupyter.org](https://jupyter.org)
- ❖ Binder [mybinder.org](https://mybinder.org)
- ❖ Colab [colab.research.google.com](https://colab.research.google.com)



# Portability and Continuous Integration

```
33 lines (26 sloc) | 553 Bytes
Raw Blame ⌂ ⌄ ⌁ ⌂

1 name: Build Status
2
3 defaults:
4   run:
5     shell: bash
6
7 on:
8   push:
9     branches: [ master ]
10  pull_request:
11    branches: [ master ]
12
13 jobs:
14   build:
15     strategy:
16       matrix:
17         platforms: [ubuntu-latest, macos-latest, windows-latest]
18       runs-on: ${{ matrix.platform }}
19
20 steps:
21   - uses: actions/checkout@v2
22
23   - uses: actions/setup-python@v1
24     with:
25       python-version: 3.8
26   - run: |
27     pip install pytest
28
29   - run: |
30     pip install -r requirements.txt
31
32   - run: |
33     PYTHONPATH=. pytest
```

## Merge pull request #260 from slayoo/setup\_settings

master



f19542d



Re-run jobs

### Build Status

on: push

✓ build (ubuntu-latest)

✓ build (macos-latest)

✓ build (windows-latest)

### build (windows-latest)

succeeded 12 hours ago in 8m 35s

Search logs

...

> ✓ Set up job 3s

> ✓ Run actions/checkout@v2 8s

> ✓ Run actions/setup-python@v1 0s

> ✓ Run pip install pytest 10s

> ✓ Run pip install -r requirements.txt 1m 57s

> ✓ Run PYTHONPATH=. pytest 6m 13s

> ✓ Post Run actions/checkout@v2 4s

> ✓ Complete job 0s

README.md

[build](#)  passing [coverage](#)  61%

## PySDM

PySDM is a package for simulating the dynamics of population of particles immersed in moist air based (a.k.a. super-droplet) approach to represent aerosol/cloud/rain microphysics. The package high-performance implementation of the Super-Droplet Method (SDM) Monte-Carlo algorithm for collisional growth ([Shima et al. 2009](#)), hence the name. PySDM has two alternative parallel number available: multi-threaded CPU backend based on [Numba](#) and GPU-resident backend built on top

## Demos:

- [Shima et al. 2009 Fig. 2](#)  [launch](#)   [Open in Colab](#)  
(Box model, coalescence only, test case employing Golovin analytical solution)
- [Berry 1967 Figs. 6, 8, 10](#)  [launch](#)   [Open in Colab](#)  
(Box model, coalescence only, test cases for realistic kernels)

# Highlights

- New pythonic implementation of SDM
- CPU/GPU parallelization
- Adaptive time stepping schemes  
for coalescence and condensation
- Low entry threshold:
  - for users (Jupyter Notebooks “in the cloud”)
  - for developers (2.1 kLOC of tests/ 3.8 kLOC of source)

MORE:

[www.ap.uj.edu.pl/diplomas/141204](http://www.ap.uj.edu.pl/diplomas/141204)

[www.github.com/atmos-cloud-sim-uj/PySDM](https://github.com/atmos-cloud-sim-uj/PySDM)

[www.github.com/piotrbartman](https://github.com/piotrbartman)

[piotr.bartman@doctoral.uj.edu.pl](mailto:piotr.bartman@doctoral.uj.edu.pl)

funding acknowledgment:

Foundation for Polish Science / European Union